

IN THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims regarding the present application:

1. (previously presented) A tool for selectively tightening and loosening a light bulb comprising:
 - a. means for clasping the light bulb, the clasping means configured to have an adjustable dimension for clasping a correspondingly sized light bulb; and
 - b. means for activating the clasping means, the activating means is configured for remote communication with the clasping means, wherein the activating means sends control communications to move the clasping means in a first direction and a second direction, wherein the control communications are sent wirelessly from the means for activating to the means for clasping.
2. (original) The tool according to claim 1 further comprising means for setting the clasping means in a desired configuration to engage the light bulb, wherein the setting means is coupled to the clasping means.
3. (original) The tool according to claim 2 wherein the means for setting further comprises a means for varying the adjustable dimension, wherein the varying means is coupled to the activating means.
- 4-5. (canceled)
6. (previously presented) The tool according to claim 1 wherein the clasping means and the activating means are coupled to a tubular member.
7. (canceled).
8. (original) The tool according to claim 6 further comprising means for selectively adjusting an overall length of the tubular member.

9. (original) The tool according to claim 1 wherein the means for activating is powered by a DC voltage source.
10. (original) The tool according to claim 1 wherein the means for activating is powered by an AC voltage source.
11. (previously presented) A light bulb changing tool comprising:
 - a. a motorized clasping mechanism configured to engage a light bulb, the motorized clasping mechanism configured along an axis and to actuate in a first direction and a second direction; and
 - b. an electronic drive unit configured for remote communication with the motorized clasping mechanism, wherein the electronic drive unit sends control communications to drive the motorized clasping mechanism to selectively move in the first direction and the second direction, wherein the control communications are sent wirelessly from the electronic drive unit to the motorized clasping mechanism.
12. (original) The tool according to claim 11 further comprising an arm member for positioning the motorized clasping mechanism in a desired configuration to engage the light bulb, wherein the arm member is coupled to the motorized clasping mechanism.
13. (original) The tool according to claim 11 wherein the motorized clasping mechanism further comprises a rotator mechanism configured to rotate the motorized clasping mechanism in the first direction about the axis.
14. (original) The tool according to claim 11 wherein the motorized clasping mechanism further comprises a plurality of spring urged fingers.
15. (original) The tool according to claim 14 further comprising an adjusting mechanism configured to actuate the motorized clasping mechanism in the second direction, wherein the adjusting mechanism causes at least two of the plurality of spring urged fingers to actuate towards and away from the axis.

16-17. (canceled)

18. (previously presented) The tool according to claim 11 wherein the motorized clasp mechanism and the electronic drive unit are coupled to a tubular member.

19. (canceled)

20. (original) The tool according to claim 11 wherein the electronic drive unit is powered by a DC voltage source.

21. (original) The tool according to claim 11 wherein the electronic drive unit is powered by an AC voltage source.

22. (currently amended) A method of assembling a light bulb changing tool, the method comprising the steps of:

- a. providing a clasp mechanism configured to engage a light bulb, the clasp mechanism having an adjustable dimension; ~~and~~
- b. coupling the clasp mechanism to a cylindrical member; and
- c. ~~providing a~~ coupling a drive unit to the cylindrical member, the drive unit in remote communication with the clasp mechanism, wherein the drive unit sends control communications to electrically activate the clasp mechanism to actuate in a first direction and a second direction, wherein the control communications are sent wirelessly from the drive unit to the clasp mechanism.

23. (original) The method according to claim 22 further comprising the step of coupling an adjusting arm to the clasp mechanism, the adjusting arm configured to adjust the clasp mechanism to a desired position relative to the light bulb.

24. (currently amended) The method according to claim 22 ~~further comprising the step of coupling the clasp mechanism and the drive unit to a~~ wherein the cylindrical member is tubular member.

25-27. (canceled)

28. (previously presented) A light bulb changing tool assembly comprising:
- a. a motorized clasping mechanism for engaging a light bulb, the motorized clasping mechanism rotatable in a first direction and a second direction, the motorized clasping mechanism having a port for engaging to the cylindrical member; and
 - b. a drive control unit for wirelessly communicating with the motorized clasping mechanism to selectively move the motorized clasping mechanism in the first direction and the second direction.
29. (previously presented) The tool according to claim 28 further comprising an arm member for positioning the motorized clasping mechanism in a desired configuration to engage the light bulb, wherein the arm member is coupled to the motorized clasping mechanism.
30. (previously presented) The tool according to claim 28 wherein the motorized clasping mechanism further comprises a rotator mechanism configured to rotate the motorized clasping mechanism in the first direction about the axis.
31. (previously presented) The tool according to claim 28 wherein the motorized clasping mechanism further comprises a plurality of spring urged fingers.
32. (previously presented) The tool according to claim 31 further comprising an adjusting mechanism configured to actuate the motorized clasping mechanism in the second direction, wherein the adjusting mechanism causes at least two of the plurality of spring urged fingers to actuate towards and away from the axis.
33. (previously presented) The tool according to claim 28 wherein the motorized clasping mechanism and the electronic drive unit are coupled to a tubular member.